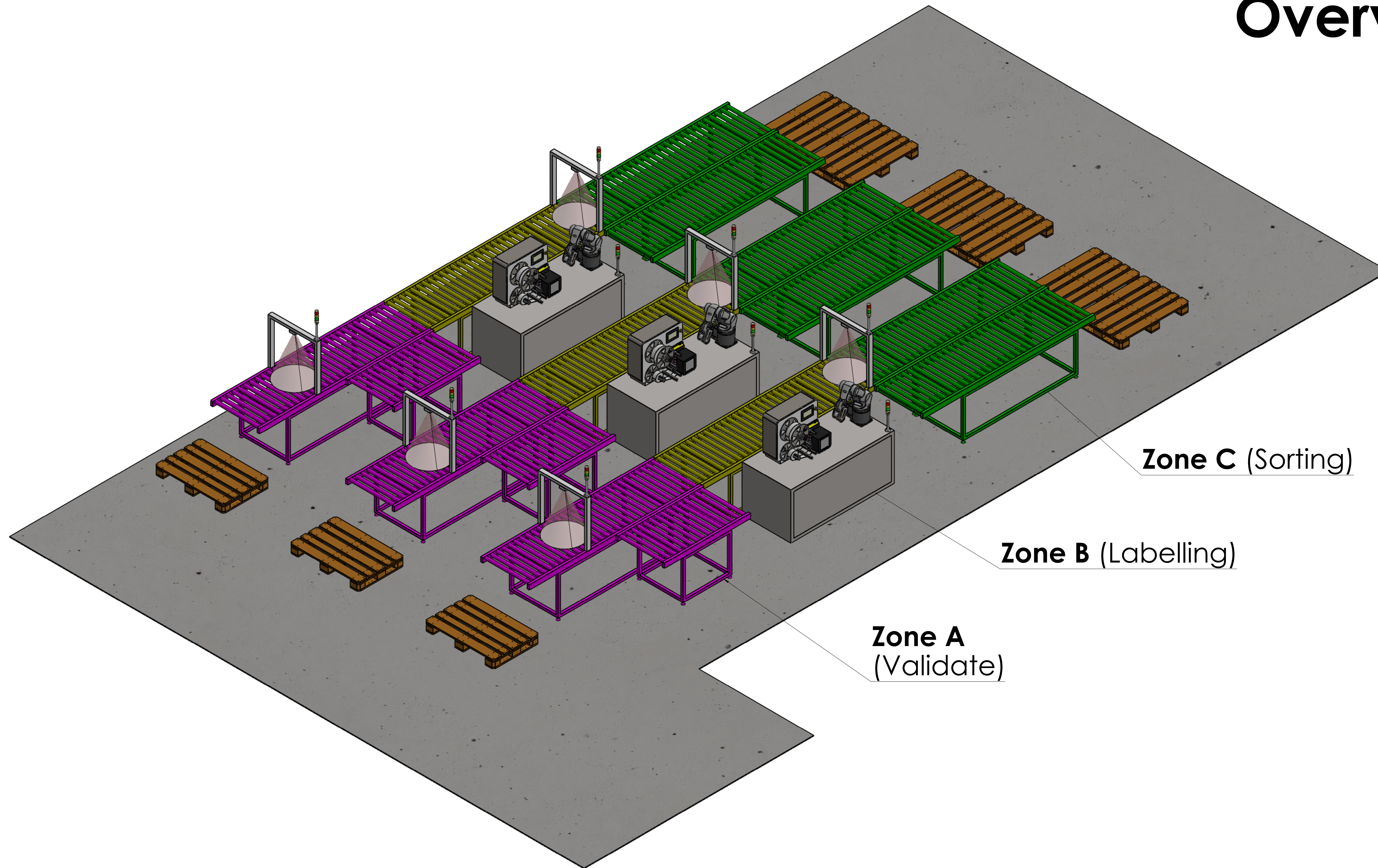


Overview Receiver

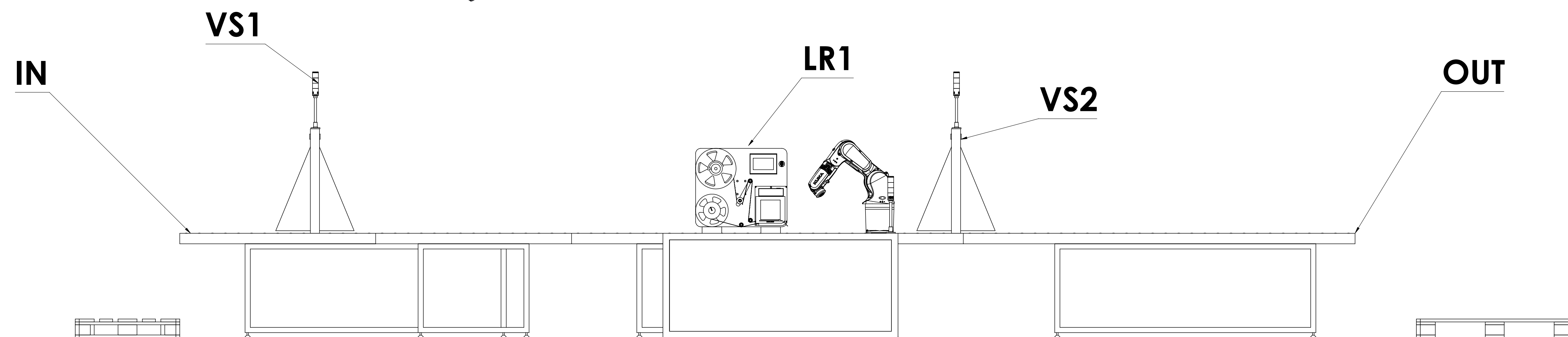


ZoneA

1. Received from forwarder
2. Load to conveyor by pallet and auto scan HAWB
3. Scan supplier label and auto RT
4. Validate Supplier label
 - 4.1 Success : Next to ZoneB
 - 4.2 Failed : Reject to Human recheck

ZoneB

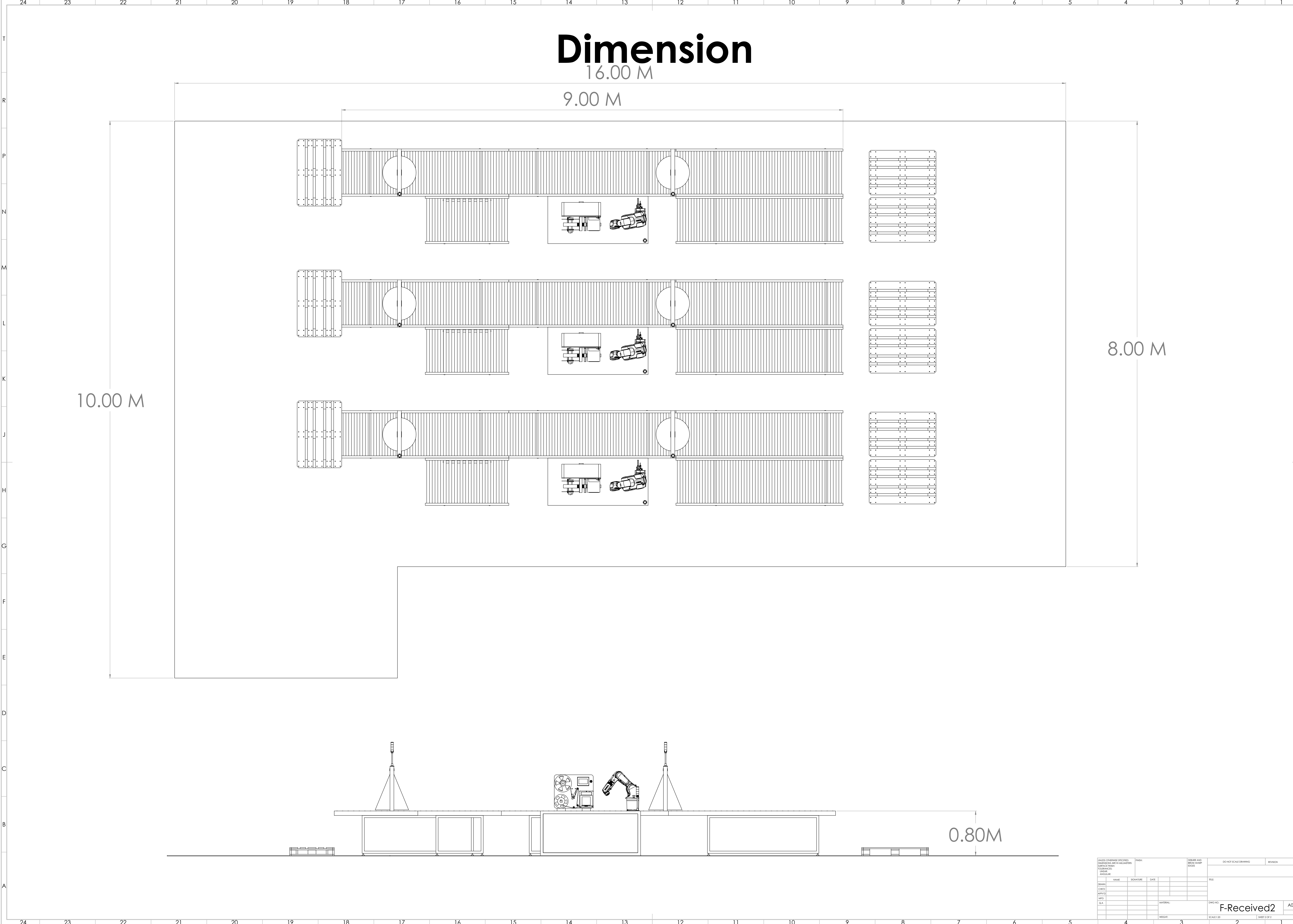
1. Received from ZoneA
2. Auto print RT detail on packaging
3. Labelling with robot & zebra ze500 (LR1)
4. Varidate Label Type1 or Type2 or Other&Unknow
 - 4.1 Type1 : Next to **ZoneC Type1**
 - 4.2 Type2 : Next to **ZoneC Type2**
 - 4.3 Other&Unknow : Reject to Human recheck



VS = Vision Camera (**KEYENCE**)
L = Labelling Machine with Stand (**Zebra ZE500**)
R = Robot Arm (**KUKA KR4 R600**)

KEYENCE **KUKA**

[illegible]



| | | | | | | | | | | |
|--|-----------|------|--|--------|--|---------------------------------------|--|----------------------|--|----------|
| TOLERANCES UNLESS SPECIFIED: DIMENSIONS ARE IN MILLIMETERS SURFACE FINISH: TOLERANCES: UNLESS SPECIFIED | | | | FINISH | | TOLERANCE AND BREAK SHARP EDGES | | DO NOT SCALE DRAWING | | REVISION |
| NAME | SIGNATURE | DATE | | | | | | TITLE | | |
| DRAWN | | | | | | | | OWNER'S USE | | |
| CHECKED | | | | | | | | | | |
| APPROVED | | | | | | | | | | |
| INFO | | | | | | | | | | |
| DATE | | | | | | | | MATERIAL | | |
| | | | | | | | | WEIGHT | | |
| | | | | | | | | SCALE 1:20 | | |
| | | | | | | | | SHEET 2 OF 2 | | |

F-Received2

A0