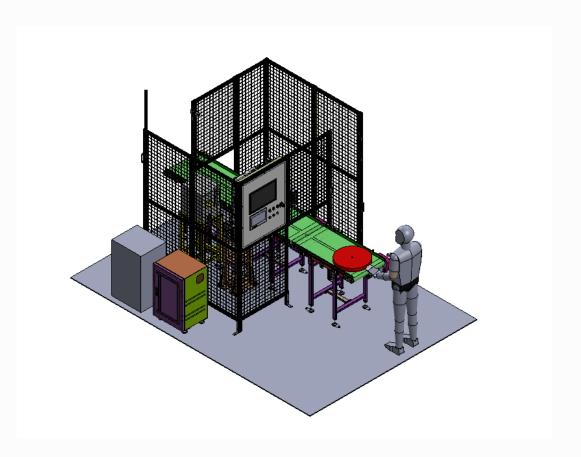
Auto labeling machine Made for PANASONIC AUTOMOTIVE SYSTEMS ASIA PACIFIC CO.,LTD.

TOMAS TECH CO., LTD.

Agenda

- ► Packet material
- ► Layout machine
- ► Process flow
- ► Operation flow

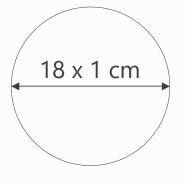


Packet material

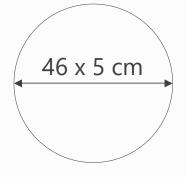
Packet material

| | | ₽ |
|-------------|--------------------|-------------|
| ขนาดของ Pac | ket Material | |
| No. | Туре | Size |
| 1 | Small Reel เล็กสุด | 18x1 cm. |
| | Big Reel ใหญ่สุด | 46x5 cm |
| 3 | PCB | 25x25x8 cm |
| | กล่อง | |
| 4 | -สูงสุด | 38x40x26 cm |
| 5 | -กว้างสุด | 41x41x5 cm |
| 6 | -ยาวสุด | 27x64x21 cm |
| 7 | ′ -เล็กสุด | 19x19x5 cm |
| | | |
| | | |

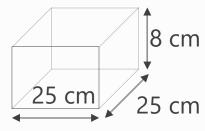




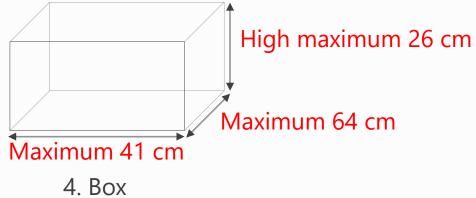
1. Small Reel



2. Big Reel



3. PCB



Packet material

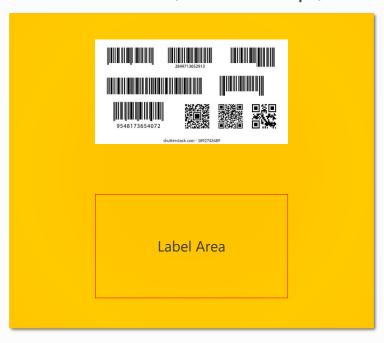
Packet materials that can participate in the Auto process

Reels





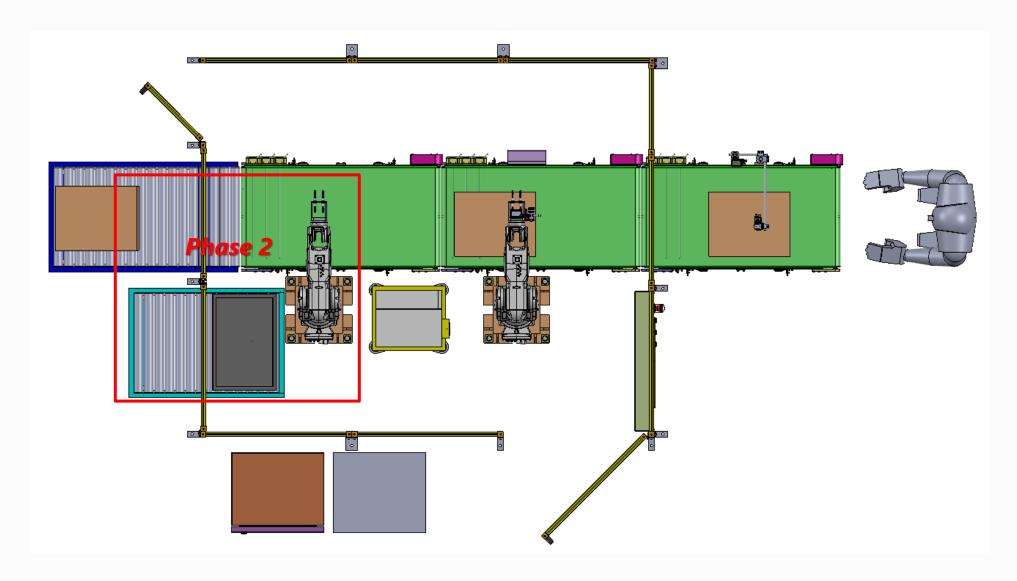
Box or PCB (label on top)



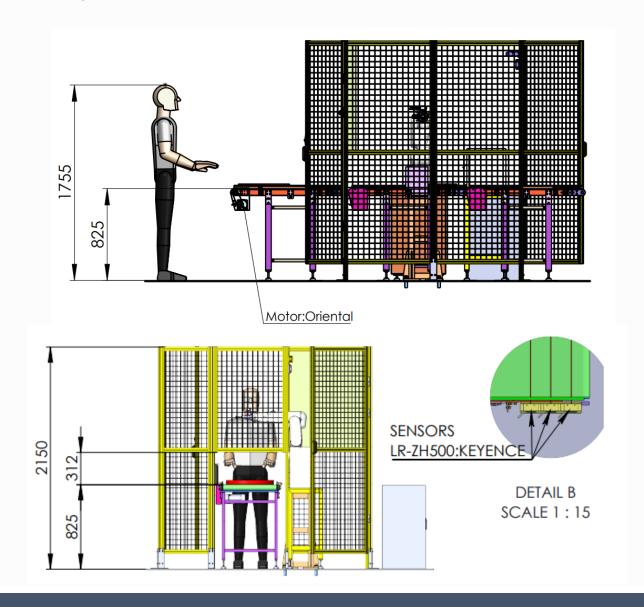


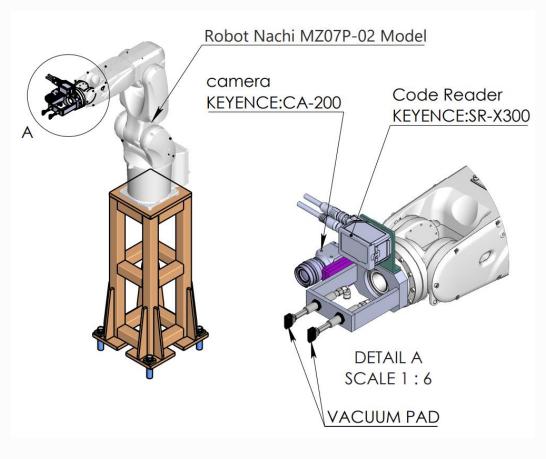
Layout machine

Layout machine

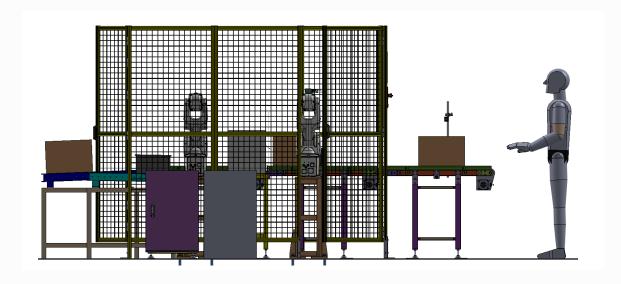


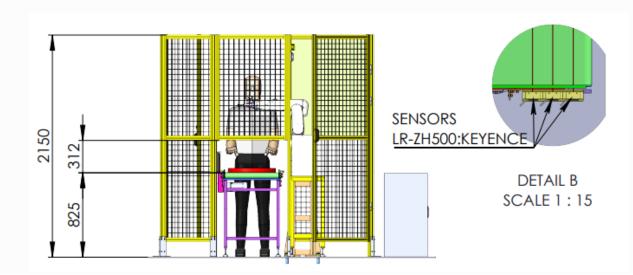
Layout machine Phase 1

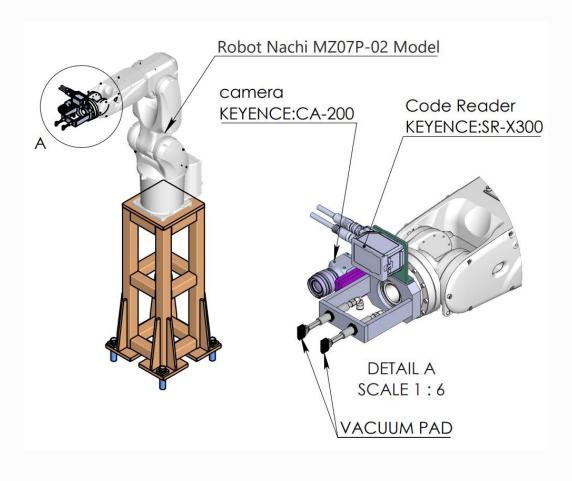




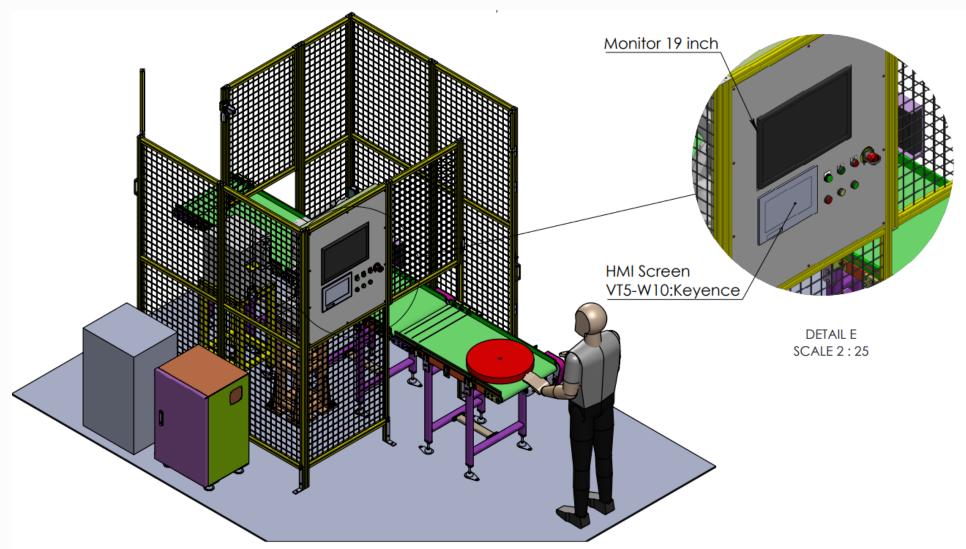
Layout machine Phase 2





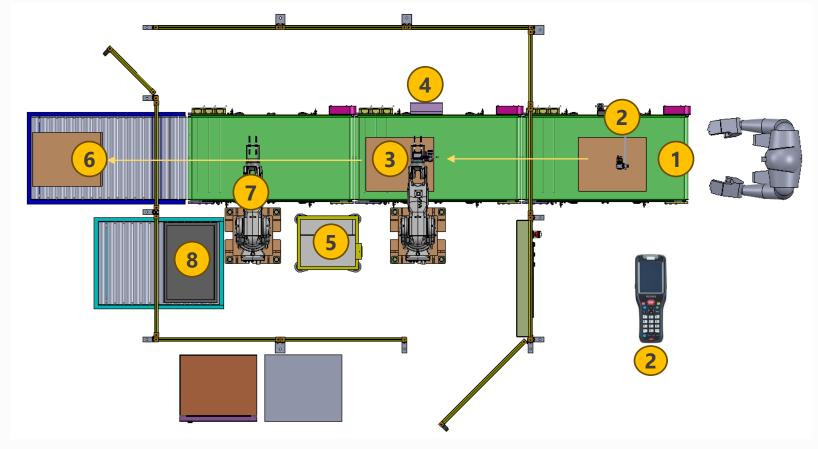


Layout machine



Process flow

Process flow

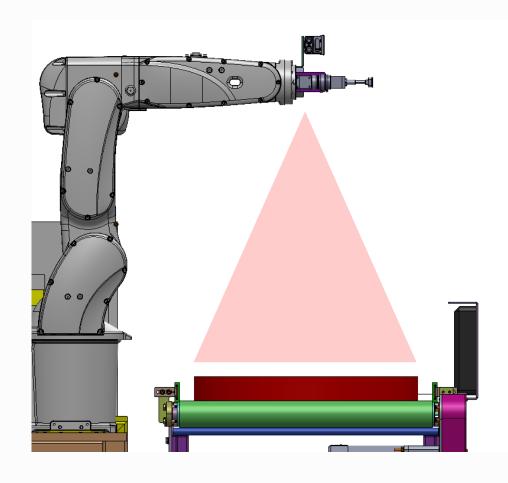


Phase 1

Phase 2

- Place the work piece on the first Conveyor, after which the Conveyor will transport the work piece to the second point.
- 2. Use SR-Reader *In cases where work cannot be read with SR, Handy will be used instead. scan at work for select model and send the model to the computer to print labels
- 3. When the workpiece reaches the third position, the robot will use the camera to take pictures to find the current sticker position. and make an offset from the current position to the position to be pasted
- 4. After the sticker is finished, the robot will lift the Z axis and rotate the SR-Reader to read the information after the sticker is finished.
- 5. In the case of a model with RFID, information will be written as well.
- 6. After data confirmation is complete, the workpiece will be sent to the load-out location.
- 7. After the auto labeling process is completed, point number 7 will be the work sorting point. In order to put it in the box, point 8, in the case of the work being Reels, if it is a Box, it will be released to point 6.

Process flow



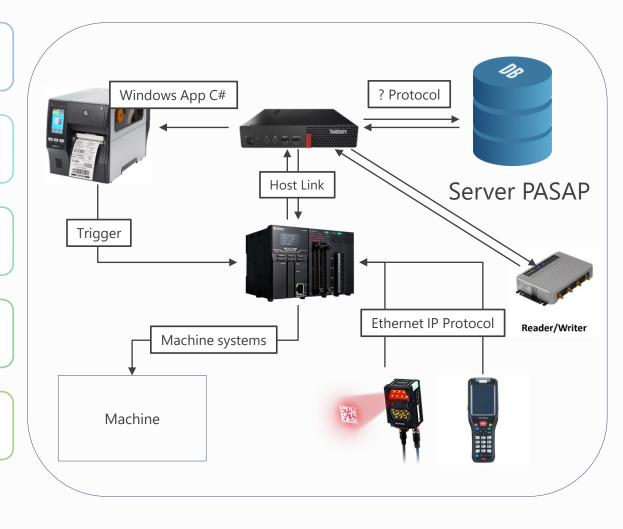




Operation flow

RFID Read/Writer

• Preparing data for INV.Number and INV.Order Register invoice • By SR-Reader/Handy send to Barcode system Read Part Number • By Robot received trigger by sensor Auto labeling • PLC SR-Reader read from sticker label send to Barcode systems Duplicate check • PLC Read from RFID and send to RFID systems



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Contact



info@tomastc.com



TH/EN: +66-81-012-6064 (Anek) JP/TH/EN: +66-94-552-3097 (Nozaki)



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http://www.tomastc.com



7/1(3C) Soi Sukhumvit 103 (Udomsuk 46) Sukhumvit Bang Na, Bangkok 10260

